



2013 Technological Studies

Intermediate 2

Finalised Marking Instructions

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Part One: General Marking Principles for Technological Studies Intermediate 2

This information is provided to help you understand the general principles you must apply when marking candidate responses to questions in this Paper. These principles must be read in conjunction with the specific Marking Instructions for each question.

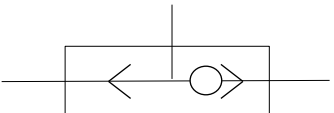
- (a) Marks for each candidate response must always be assigned in line with these general marking principles and the specific Marking Instructions for the relevant question. If a specific candidate response does not seem to be covered by either the principles or detailed Marking Instructions, and you are uncertain how to assess it, you must seek guidance from your Team Leader/Principal Assessor. You can do this by posting a question on the Marking Team forum or by e-mailing/phoning the e-marker Helpline.
- (b) Marking should always be positive ie, marks should be awarded for what is correct and not deducted for errors or omissions.

GENERAL MARKING ADVICE: Technological Studies Intermediate 2

The marking schemes are written to assist in determining the “minimal acceptable answer” rather than listing every possible correct and incorrect answer. The following notes are offered to support Markers in making judgements on candidates’ evidence, and apply to marking both end of unit assessments and course assessments.

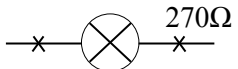
Part Two: Marking Instructions for each Question

SECTION A

| Question | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|-----|--|----------|--|
| 1 | a | Error detector | 1 | |
| | b i | Negative (feedback) | 1 | Ignore lack/‘feedback’ |
| | ii | Maintaining desired level | 1 | Reducing the error |
| | c | <p>The position is set.</p> <p>The position sensor sends the actual position to the error detector.</p> <p>This signal is compared with the set position.</p> <p>If there is an error then the control unit will switch on the motor, moving the telescope to the desired position.</p> <p>When there is no error detected then the motor will stop.</p> <p>1 mark for each correct statement</p> | 3 | |
| 2 | a | <p>Component ⑤ – Reservoir</p> <p>Valve ② – Diaphragm 3/2 valve spring return</p> | 1 1 | All parts of the name for valve – 1 mark |
| | b | <p>... valve ② is activated sending air to valve ③. When valve ③ is activated pilot air will be sent to valve ④, causing the cylinder to outstroke. After a set time delay, pilot air is sent to valve ④ causing the cylinder to instroke again.</p> <p>1 mark for each correct statement</p> | 4 | |
| | c i | Shuttle valve | 1 | |
| | ii |  | 1 | Apply FTE from (c) (i) |

| Question | | Expected Answer/s | Max Mark | Additional Guidance | | | | | | | | | | |
|----------|-------------------------------|--|----------|---|---|-------------------------------|---|--|---|--|---|--|---|--|
| 3 | a | main: low 6 1 mark if pin 2 = 0 then main 1 mark high 6 pause 10 1 mark low 6 pause 20 goto main 1 mark | 5 | Accept binary equivalent for pins Syntax must be correct | | | | | | | | | | |
| | b | i Pulse Width Modulation 1 ii space 1 | | | | | | | | | | | | |
| 4 | a | <table border="1"> <tr> <td>Z</td> <td></td> </tr> <tr> <td>0</td> <td>1 mark each output row</td> </tr> <tr> <td>1</td> <td></td> </tr> <tr> <td>0</td> <td></td> </tr> <tr> <td>1</td> <td></td> </tr> </table> | Z | | 0 | 1 mark each output row | 1 | | 0 | | 1 | | 4 | |
| Z | | | | | | | | | | | | | | |
| 0 | 1 mark each output row | | | | | | | | | | | | | |
| 1 | | | | | | | | | | | | | | |
| 0 | | | | | | | | | | | | | | |
| 1 | | | | | | | | | | | | | | |
| | b | <p>1 mark for each gate (correct symbol)</p> | 4 | | | | | | | | | | | |
| | c | CMOS | 1 | | | | | | | | | | | |

| Question | | | Expected Answer/s | Max Mark | Additional Guidance | |
|----------|---|----|---|---|---------------------|---|
| 5 | a | i | $E_k = \frac{1}{2}mv^2$ $= \frac{1}{2} \times 2500 \times 15^2$ $= 281250\text{J} \quad (281\text{kJ})$ | <p style="text-align: right;">1 mark</p> <p style="text-align: right;">1 mark</p> | 2 | |
| | | ii | $E_k = E_p = 281250\text{J}$ $h = \frac{E_p}{mg} = \frac{281250}{2500 \times 9.81}$ $= 11.47\text{m}$ | <p style="text-align: right;">1 mark (FTE)</p> <p style="text-align: right;">1 mark</p> <p style="text-align: right;">1 mark</p> | 3 | Allow FTE from (a) (i) |
| | b | i | Wind resistance, Friction, | | 1 | Cause only; not the form of energy lost |
| | | ii | Streamline, lubrication | | 1 | |
| 6 | a | i | $\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}$ $\frac{1}{R_T} = \frac{1}{100} + \frac{1}{100} + \frac{1}{270}$ $R_T = \frac{1}{0.01 + 0.01 + 0.0037}$ $= 42.2\Omega$ | <p style="text-align: right;">1 mark</p> <p style="text-align: right;">1 mark</p> <p style="text-align: right;">1 mark</p> | 3 | $R_T = \frac{R_1 R_2}{R_1 + R_2}$ $= \frac{100 \times 100}{100 + 100}$ $= 50\Omega$ <p style="text-align: right;">1 mark</p> $R_T = \frac{R_1 R_2}{R_1 + R_2}$ $= \frac{50 \times 270}{50 + 270}$ $= 42.2\Omega$ <p style="text-align: right;">1 mark</p> <p style="text-align: right;">1 mark</p> |
| | | ii | $42.2 + 390 = 432.2\Omega$ | | 1 | Allow FTE from (a) (i) |

| Question | | | Expected Answer/s | Max Mark | Additional Guidance | |
|----------|---|-----|---|---|---------------------|--------------------------|
| 6 | a | iii | $I = \frac{V}{R} = \frac{12}{432 \cdot 2}$ $= 0 \cdot 028A$ | <p>1 mark</p> <p>1 mark</p> | 2 | Allow FTE from (a) (ii) |
| | | iv | $P = IV = 0 \cdot 028 \times 12$ $= 0 \cdot 34W$ | <p>1 mark</p> <p>1 mark</p> | 2 | Allow FTE from (a) (iii) |
| | b | |  <p>accept indication anywhere on 270Ω lamp branch</p> | | 1 | |

| Question | Expected Answer/s | Max Mark | Additional Guidance |
|----------|---|----------|---|
| 7 | <pre> graph TD Start([Start]) --> D1{is train sensed} D1 -- N --> Start D1 -- Y --> L1[/lower barrier/] L1 --> D2{is limit switch pressed} D2 -- N --> Start D2 -- Y --> L2[/barrier stop/] L2 --> D3{is train sensed} D3 -- Y --> Start D3 -- N --> W1[wait 10 seconds] W1 --> L3[/barrier up/] L3 --> W2[wait 3 seconds] W2 --> L4[/barrier stop/] L4 --> Start </pre> <p> 1 mark for loop to main *1 mark both waits •1 mark both barrier stops 1 mark for correct symbols *1 mark both barrier movements </p> | 7 | <p>Decision loops must include (yes or no indication)</p> <p>If PBASIC commands are used ignore syntax but pin must be correct. (Pause 10000 and pause 3s = 1 mark)</p> |

| Question | | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|---|----|--|---------------------|---|
| 8 | a | i | Compound (gear train) | 1 | |
| | | ii | Higher gear ratio achieved without very large gears (more compact) | 1 | |
| | b | i | $\text{Velocity Ratio} = \frac{\text{Input Speed}}{\text{Output Speed}}$ $= \frac{30}{1440} \quad \mathbf{1 \text{ mark}}$ $= 0.02:1 \quad \mathbf{1 \text{ mark}}$ Or 1:48 (accept 1:50) | $\frac{20.02:1}{-}$ | Answer from given working (allowing for rounding of VR) |
| | | ii | $\frac{0.02}{1} = \frac{8}{A} \times \frac{8}{48} \quad \mathbf{1 \text{ mark}}$ $0.02 = \frac{8}{A} \times 0.1667$ $0.1199 = \frac{8}{A}$ $A = \frac{8}{0.1199} \quad \mathbf{1 \text{ mark}}$ $= 64 \text{ teeth} \quad \mathbf{1 \text{ mark}}$ | 3 | Answer from given working (allowing for rounding of VR) |

SECTION B

| Question | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|----|---|----------|------------------------|
| 9 | a | <p>...the resistance of the LDR increases, increasing the value of voltage (V_1). As V_1 increases past 0.7v the transistor saturates, activating the relay. When the start switch is pressed the motor will start.</p> <p>1 mark for each correct statement</p> | 4 | |
| | b | | | |
| | i | 400 Ω (0.4k Ω) | 1 | |
| | ii | Light Dependant Resistor | 1 | |
| | c | | | |
| | i | $I_B = \frac{I_c}{h_{FE}}$ $= \frac{48\text{mA}}{80}$ <p>1 mark</p> $= 0.6\text{mA}$ <p>1 mark</p> | 2 | |
| | ii | $V = IR$ $= 0.0006 \times 1000$ $= 0.6\text{V}$ <p>1 mark</p> $V_1 = 0.6 + 0.7$ $= 1.3\text{V}$ <p>1 mark</p> | 2 | Allow FTE from (c) (i) |
| | d | | | |
| | i | Single Pole Double Throw | 1 | |
| | ii | To allow a low voltage/current electronic circuit to control a high current/voltage electrical circuit. | 1 | |

| Question | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|---|---|----------|--|
| 10 | d | <p> 1 mark for each gate 1 mark for all power connections </p> | 4 | |
| | e | i 7404: Hex Invertor 1 mark 7408: Quad 2input AND gate 1 mark | 2 | Fully stated description for the IC number |
| | | ii TTL | 1 | |
| | | iii 5V (+/- 0.25V) | 1 | No FTE |
| | | iv to show where pin 1 is | 1 | |

| Question | | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|---|-----|---|----------|------------------------------------|
| 11 | a | i | $E_e = Pt$ $t = 3 \times 60$ $= 180 \text{ secs}$ $= 42000 \times 180$ 1 mark $= 7560 \text{kJ}$ 1 mark | 2 | |
| | | ii | $E_p = mgh$ $= 1000 \times 9.81 \times 500$ 1 mark $= 4905 \text{kJ}$ 1 mark | 2 | |
| | | iii | $\eta = \frac{E_{\text{out}}}{E_{\text{in}}}$ $= \frac{4905000}{7560000}$ 1 mark $= 0.648$ or $= 65\%$ 1 mark | 2 | Allow FTE from (a) (i) and/or (ii) |
| | b | i | friction at moving parts | 1 | Not type of energy lost |
| | | ii | Lubricate gears, bearings or 'slipper' materials used | 1 | |

| Question | | Expected Answer/s | Max Mark | Additional Guidance |
|----------|-----|--|----------|-----------------------|
| 11 | c | Warning: for b0 = 1 to 20 1 mark | 6 | For counter = 1 to 20 |
| | | <pre> high 7 pause 250 low 7 pause 250 next b0 return </pre> <p>1 mark high 1 mark low 1 mark for both pauses 1 mark 1 mark</p> | | |
| | d i | 10 seconds | 1 | |
| | | ii Gosub (warning) | 1 | Ignore label |
| | e | Shorten the length of the program/allow similar programs to be used repeatedly in the same program | 1 | |
| | f i | Electronic Erasable Programmable Read Only Memory | 1 | |
| | | ii Information can be re-written / non-volatile | 1 | |
| | | iii ROM / RAM | 1 | |

[END OF MARKING INSTRUCTIONS]